Stochastic Primal-Dual Hybrid Gradient Algorithm



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Motivation

- Convex optimization problems can often be efficiently solved as saddle point problems [1].
- In many applications (e.g. CT, parallel MRI, PET) saddle point problems are **separable** in the dual variable $y = (y_1, \ldots, y_n)$:

$$(x^{\sharp}, y^{\sharp}) \in \arg\min_{x} \max_{y} \left\{ \sum_{i=1}^{n} \langle \mathbf{A}_{i}x, y_{i} \rangle - f_{i}^{*}(y_{i}) + g(x) \right\}$$

Faster PET Reconstruction [3]

• SPDHG converges to solution of deterministic problem.



• Exploit structure by extending primal-dual hybrid gradient [1] to randomization over dual variables.

Stochastic PDHG Algorithm (SPDHG) [2]

• probability of the *i*th variable being selected: $p_i = \mathbb{P}(i \in \mathbb{S}^k) > 0$ • evaluation of \mathbf{A}_i and \mathbf{A}_i^* only for $j \in \mathbb{S}^k$

Efficient Implementation of SPDHG [3]

• example for **separable** samplings: $\mathbb{S}^k = \{i\}$ • auxiliary variable $z^k = \sum_{i=1}^n \mathbf{A}_i^* y_i^k$



• SPDHG is **faster** with more subsets (example for 20 epochs).



• SPDHG is **faster** in terms of objective decrease and PSNR.

--- PDHG

 \rightarrow SPDHG (21 subsets) - SPDHG (252 subsets)





- Initialize: $z^0 = \sum_{i=1}^n \mathbf{A}_i^* y_i^0$, $\overline{z}^0 = z^0$ • $x^{k+1} = \operatorname{prox}_{\tau q}(x^k + \tau \overline{z}^k)$
- Select $j \in \{1, ..., n\}$ $y_i^{k+1} = \begin{cases} \operatorname{prox}_{\sigma_i f_i^*}(y_i^k - \sigma_i \mathbf{A}_i x^{k+1}) & \text{if } i = j \\ y_i^k & \text{else} \end{cases}$ $\blacktriangleright \Delta z = \mathbf{A}_i^* (y_i^{k+1} - y_i^k)$ $\triangleright z^{k+1} = z^k + \Delta z, \quad \overline{z}^{k+1} = z^{k+1} + \frac{\theta}{p_i} \Delta z$

Convergence of SPDHG [2]

Theorem. Let (x^{\sharp}, y^{\sharp}) be a saddle point and the random sampling \mathbb{S}^k be iid and separable. Choose $\theta = 1$ and σ_i, τ such that

 $\sigma_i \tau \|\mathbf{A}_i\|^2 < p_i$.

Then the iterates of SPDHG **converge** to a saddle point in a Bregman sense almost surely:

Faster by Acceleration [2]

• Accelerated SPDHG converges as $\mathcal{O}(1/k^2)$ for ROF denoising.



Conclusions

- Stochastic optimization for dual separable cost functionals.
- Generalization of PDHG as it is recovered for $n = 1, p_1 = 1$.

$D_q^{r^{\sharp}}(x^k, x^{\sharp}), \ D_{f^*}^{q^{\sharp}}(y^k, y^{\sharp}) \to 0$ a.s.

Moreover, the ergodic sequence $(x_K, y_K) = \frac{1}{K} \sum_{k=1}^{K} (x^k, y^k)$ converges to a saddle point with rate O(1/K):

$\mathbb{E}\left\{D_g^{r^{\sharp}}(x_{\mathcal{K}}, x^{\sharp}) + D_{f^*}^{q^{\sharp}}(y_{\mathcal{K}}, y^{\sharp})\right\} \leq \frac{C}{\kappa}$

• see [2] for other samplings, acceleration and linear convergence

• **Convergence rates** for SPDHG in expectation.

- Faster PET reconstruction: 10x speed-up on clinical data.
- SPDHG can be **accelerated** to achieve $\mathcal{O}(1/k^2)$ convergence.
- [1] A. Chambolle and T. Pock. "A First-Order Primal-Dual Algorithm for Convex Problems with Applications to Imaging". J Math Imaging Vision 40.1 (2011), pp. 120–145.
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